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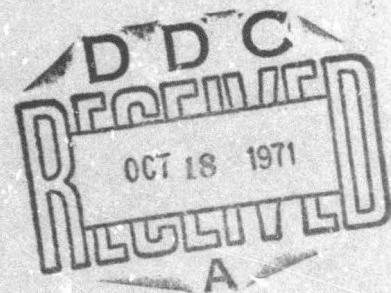
REPORT NO. 1541

## A NUMERICAL SOLUTION FOR FLOW BETWEEN ROTATING AND STATIONARY FINITE DISKS

by

Donald H. McCoy

June 1971



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Unclassified

Security Classification

DOCUMENT CONTROL DATA - R & D

(Security classification of title, body of abstract and indexing annotation must be entered when the overall report is classified)

1. ORIGINATING ACTIVITY (Corporate author)  
US Army Aberdeen Research and Development Center  
Ballistic Research Laboratories  
Aberdeen Proving Ground, Maryland 21005

2a. REPORT SECURITY CLASSIFICATION

Unclassified

2b. GROUP

3. REPORT TITLE

A NUMERICAL SOLUTION FOR FLOW BETWEEN ROTATING AND STATIONARY FINITE DISKS

4. DESCRIPTIVE NOTES (Type of report and inclusive dates)

5. AUTHOR(S) (First name, middle initial, last name)

Donald H. McCoy

6. REPORT DATE

June 1971

7a. TOTAL NO. OF PAGES

55

7b. NO. OF REFS

4

8. CONTRACT OR GRANT NO.

9a. ORIGINATOR'S REPORT NUMBER(S)

10. PROJECT NO. RDT&E 1T562603A041

BRL Report No. 1541

11.

9b. OTHER REPORT NO(S) (Any other numbers that may be assigned this report)

12.

10. DISTRIBUTION STATEMENT

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its distribution is unlimited.

11. SUPPLEMENTARY NOTES

12. SPONSORING MILITARY ACTIVITY

US Army Materiel Command  
Washington, D. C.

13. ABSTRACT

The velocity field and pressure distribution between stationary and rotating finite disks are obtained by a finite difference solution of the Navier-Stokes equations and the continuity equation using an explicit scheme developed by Chorin [1]. These numerical results are compared with the results of "infinite disk" solutions. In the range of interest for viscometer applications, the velocity and pressure are adequately represented by the infinite disk solutions.

DD FORM 1 NOV 1973

REPLACES DD FORM 1473, 1 JAN 64, WHICH IS  
OCCURRENT FOR ARMY USE.

Unclassified

Security Classification

Unclassified  
Security Classification

14. KEY WORDS	LINK A		LINK B		LINK C	
	ROLE	WT	ROLE	WT	ROLE	WT
Navier-Stokes Equations Fluid Flow Viscometer						

Security Classification

BALLISTIC RESEARCH LABORATORIES

REPORT NO. 1541

JUNE 1971

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RDT&E Project No. 1T562603A041

ABERDEEN PROVING GROUND, MARYLAND

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DHMcCoy/ajb  
Aberdeen Proving Ground, Md.  
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## TABLE OF SYMBOLS

Symbol	Definition
D	Artificial density
N	Number of iterations
p	Pressure
P	Dimensionless pressure, $D/\delta$
$(r, \theta, z)$	Cylindrical coordinates
$(R, \theta, Z)$	Dimensionless cylindrical coordinates
$\bar{R}$	Maximum radial distance
$R_e$	Reynolds number
t	Time
T	Dimensionless time
u	Radial velocity
U	Dimensionless radial velocity
$U_\infty$	Dimensionless radial velocity from the infinite disk solution

$v$	<b>Tangential velocity</b>	
$V$	<b>Dimensionless tangential velocity</b>	
$w$	<b>Axial velocity</b>	
$W$	<b>Dimensionless axial velocity</b>	
$\bar{z}$	<b>Maximum axial distance</b>	
$\delta$	<b>Artificial compressibility factor</b>	
$\lambda$	<b>Ratio, <math>\bar{z}/\bar{R}</math></b>	
$\mu$	<b>Viscosity</b>	
$\nu$	<b>Kinematic viscosity, <math>\mu/\rho</math></b>	
$\rho$	<b>Density</b>	
$\Omega$	<b>Angular velocity</b>	
	<b>Reynolds number</b>	
	<b>Time</b>	
	<b>Dimensionless time</b>	
	<b>Radius velocity</b>	
	<b>Dimensionless radius velocity</b>	
	<b>Dimensionless tangential velocity</b>	
	<b>Dimensionless axial velocity</b>	

## I. INTRODUCTION

The problem of practical interest to be solved can be stated as follows: An incompressible Newtonian liquid is contained between an upper, stationary disk and a lower, rotating disk. Determine the velocity field and pressure distribution of the fluid in motion.

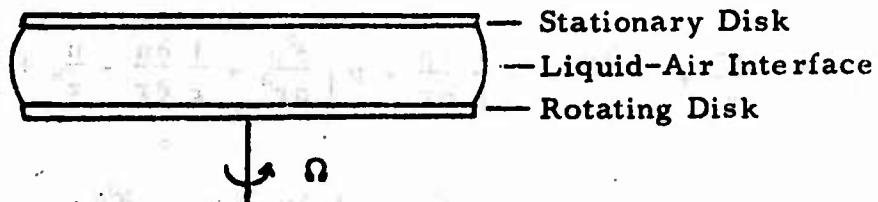


Figure 1. Physical Configuration

By presenting accurate numerical solutions to the Navier-Stokes equations, this paper makes possible an effective determination of the nature of inertial secondary motions in a rotating disk viscometer having disks of finite radii. Previous considerations of the problem have assumed that the disks are of infinite radii, resulting in solutions involving numerical and analytical approximations [2, 3]. A comparison will be made of the velocity distributions obtained with disks of finite radii and those having radii assumed to be infinite.

## II. THE EQUATIONS OF MOTION

The equations governing flow consist of those of Navier-Stokes together with the equation for continuity. These, as used in this paper, are for a cylindrical coordinate system ( $r, \theta, z$ ) with rotational symmetry and incompressibility assumed. The equations are written as follows [4]:

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial r} + \frac{v^2}{r} + w \frac{\partial u}{\partial z} = - \frac{1}{\rho} \frac{\partial p}{\partial r} + \nu \left[ \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} - \frac{u}{r^2} + \frac{\partial^2 u}{\partial z^2} \right] \quad (1)$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial r} + \frac{uv}{r} + w \frac{\partial v}{\partial z} = \nu \left[ \frac{\partial^2 v}{\partial r^2} + \frac{1}{r} \frac{\partial v}{\partial r} - \frac{v}{r^2} + \frac{\partial^2 v}{\partial z^2} \right] \quad (2)$$

$$\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial r} + w \frac{\partial w}{\partial z} = - \frac{1}{\rho} \frac{\partial p}{\partial z} + \nu \left[ \frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \frac{\partial w}{\partial r} + \frac{\partial^2 w}{\partial z^2} \right] \quad (3)$$

$$\frac{u}{r} + \frac{\partial u}{\partial r} + \frac{\partial w}{\partial z} = 0. \quad (4)$$

Here,  $u$ ,  $v$ , and  $w$  represent, respectively, velocities in the radial, tangential, and axial directions.  $\rho$  is density;  $p$  is pressure; and  $\nu$  is kinematic viscosity. The radius of each disk is  $R$ ; the spacing between them is  $Z$ ; and the angular velocity of the rotating disk is  $\Omega$ .

The above equations are normalized according to the following procedure:

Primary Variable	Normalizing Quantity	Normalized Variable
$u, v, w$	$\bar{R}\Omega$	$U, V, W$
$r$	$\bar{R}$	$R$
$z$	$\bar{z}$	$Z$
$t$	$\bar{z}/\bar{R}\Omega$	$T$
$p$	$\rho \bar{R}^2 \Omega^2$	$P$

The normalized equations are

$$\frac{\partial U}{\partial T} + \lambda \left( U \frac{\partial U}{\partial R} - \frac{V^2}{R} \right) + W \frac{\partial U}{\partial Z} = -\lambda \frac{\partial P}{\partial R} + \frac{1}{R_e} \left[ \lambda^2 \left( \frac{\partial^2 U}{\partial R^2} + \frac{1}{R} \frac{\partial U}{\partial R} - \frac{U}{R^2} \right) + \frac{\partial^2 U}{\partial Z^2} \right] \quad (5)$$

$$\frac{\partial V}{\partial T} + \lambda \left( U \frac{\partial V}{\partial R} + \frac{UV}{R} \right) + W \frac{\partial V}{\partial Z} = \frac{1}{R_e} \left[ \lambda^2 \left( \frac{\partial^2 V}{\partial R^2} + \frac{1}{R} \frac{\partial V}{\partial R} - \frac{V}{R^2} \right) + \frac{\partial^2 V}{\partial Z^2} \right] \quad (6)$$

$$\frac{\partial W}{\partial T} + \lambda \left( U \frac{\partial W}{\partial R} + W \frac{\partial W}{\partial Z} \right) = - \frac{\partial P}{\partial Z} + \frac{1}{R_e} \left[ \lambda^2 \left( \frac{\partial^2 W}{\partial R^2} + \frac{1}{R} \frac{\partial W}{\partial R} \right) + \frac{\partial^2 W}{\partial Z^2} \right] \quad (7)$$

$$\lambda \left( \frac{U}{R} + \frac{\partial U}{\partial R} \right) + \frac{\partial W}{\partial Z} = 0 \quad (8)$$

where  $R_e = \frac{\bar{z} \bar{R} \Omega}{\nu}$  and  $\lambda = \bar{z}/\bar{R}$ .

The boundary conditions used are shown in Figure 2.

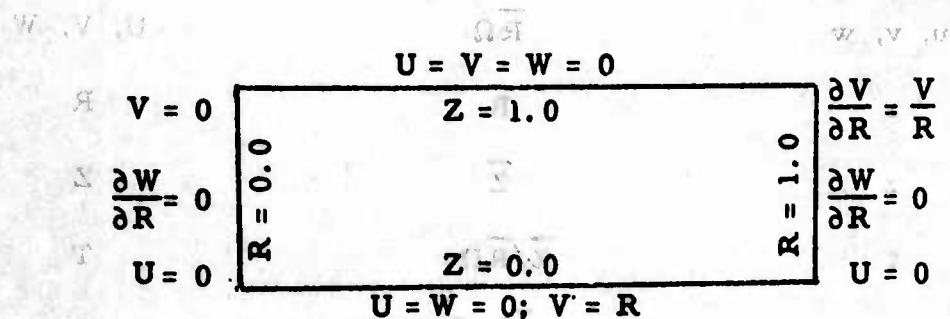


Figure 2. Boundary Conditions

The rotating plate is at  $Z = 0$  and the stationary one at  $Z = 1$ .

$R = 0$  is the axis of rotation and  $R = 1$  is the liquid-air interface which is assumed to be planar.

The Reynolds Number,  $R_e$ , represents the measure of inertial stresses relative to viscous stresses. Viscometers are usually analyzed by considering the "inertialess" limit of  $R_e \rightarrow 0$ , in which case the flow consists of circular streamlines. Viscometers generally operate with a gap-to-radius ratio,  $\lambda$ , of less than 0.05 and with the product  $\lambda R_e$  less than unity.

### III. NUMERICAL PROCEDURE

To solve the Navier-Stokes equations, Chorin's explicit technique is used. An artificial compressibility factor,  $\delta$ , is introduced into the equations of motion. Hence the continuity equation is replaced by

$$\frac{\partial D}{\partial T} = -\lambda \left( \frac{U}{R} + \frac{\partial U}{\partial R} \right) - \frac{\partial W}{\partial Z} \quad (9)$$

where  $P = D/\delta$  is an artificial equation of state.

Equations (5), (6), (7), and (9) are put into finite difference form by means of a DuFort-Frankel scheme, (details are obtained from Chorin [1]), and the resultant equations appearing below are then utilized in the computing procedure:

$$U(T^+) = \left\{ -\frac{\lambda \Delta T}{\Delta R} U [U(R^+) - U(R^-)] \right.$$

7. *Final Step: Maximum* . . . . .

$$+ 2 \lambda \Delta T \frac{V^2}{R}$$

be obtained as the value of the temperature difference  $\Delta T$  is the value of  $U(R^+)$  and  $U(R^-)$  respectively.

$$- \frac{\Delta T}{\Delta Z} W [U(Z^+) - U(Z^-)]$$

and finally

$$(1) \quad \frac{W \lambda \Delta T}{\delta \Delta R} [D(R^+) - D(R^-)]$$

$$+ \frac{2 \lambda^2 \Delta T}{R_e \Delta R^2} [U(R^+) + U(R^-) - U(T^-)]$$

$$+ \frac{\lambda^2 \Delta T}{R_e \Delta R} \frac{[U(R^+) - U(R^-)]}{R}$$

where  $R_e$  is the equivalent resistance of the bridge.

$$- \frac{2 \lambda^2 \Delta T}{R_e} \frac{U}{R^2}$$

$$+ \frac{2 \Delta T}{R_e \Delta Z^2} [U(Z^+) + U(Z^-) - U(T^-)]$$

$$+ U(T^-) \} / \left\{ 1 + \frac{2 \lambda^2 \Delta T}{R_e \Delta R^2} + \frac{2 \Delta T}{R_e \Delta Z^2} \right\} \quad (10)$$

$$V(T^+) = \left\{ -\frac{\lambda \Delta T}{\Delta R} U [V(R^+) - V(R^-)] \right.$$

$$- 2\lambda \Delta T \frac{UV}{R}$$

$$- \frac{\Delta T}{\Delta Z} W [V(Z^+) - V(Z^-)]$$

$$+ \frac{2\lambda^2 \Delta T}{R_e \Delta R^2} [V(R^+) + V(R^-) - V(T^-)]$$

$$+ \frac{\lambda^2 \Delta T}{R_e \Delta R} \frac{[V(R^+) - V(R^-)]}{R}$$

$$- \frac{2\lambda^2 \Delta T}{R_e} \frac{V}{R^2}$$

$$+ \frac{2\Delta T}{R_e \Delta Z^2} [V(Z^+) + V(Z^-) - V(T^-)]$$

$$+ V(T^-) \} / \left\{ 1 + \frac{2\lambda^2 \Delta T}{R_e \Delta R^2} + \frac{2\Delta T}{R_e \Delta Z^2} \right\} \quad (11)$$

$$W(T^+) = \left\{ -\frac{\lambda \Delta T}{\Delta R} U [W(R^+) - W(R^-)] \right. \quad (12)$$

$$- \frac{\Delta T}{\Delta Z} W [W(Z^+) - W(Z^-)]$$

$$- \frac{\Delta T}{\delta \Delta Z} [D(Z^+) - D(Z^-)]$$

$$+ \frac{2\lambda^2 \Delta T}{R_e \Delta R^2} [W(R^+) + W(R^-) - W(T^-)]$$

$$+ \frac{\lambda^2 \Delta T}{R_e \Delta R} \frac{[W(R^+) - W(R^-)]}{R}$$

$$+ \frac{2 \Delta T}{R_e \Delta Z^2} [W(Z^+) + W(Z^-) - W(T^-)]$$

$$+ W(T^-) \} / \left\{ 1 + \frac{2\lambda^2 \Delta T}{R_e \Delta R^2} + \frac{2 \Delta T}{R_e \Delta Z^2} \right\} \quad (12)$$

$$D(T^+) = -2\lambda \Delta T \frac{U}{R}$$

$$- \frac{\lambda \Delta T}{\Delta R} [U(R^+) - U(R^-)]$$

$$- \frac{\Delta T}{\Delta Z} [W(Z^+) - W(Z^-)] + D(T^-) \quad (13)$$

where  $U(R^+) = U(R + \Delta R, Z, T)$ ;

$U(R^-) = U(R - \Delta R, Z, T)$ ; etc.

Equations (10) through (13) are applicable only at interior points. For the various boundaries, the following equations were developed using for the purpose one-sided differences.

At the centerline, ( $R = 0$ ),

$$U = 0 \quad (14)$$

$$V = 0 \quad (15)$$

$$W(T^+) = \left\{ - \frac{\Delta T}{\Delta Z} W [W(Z^+) - W(Z^-)] \right.$$

$$- \frac{\Delta T}{\delta \Delta Z} [D(Z^+) - D(Z^-)]$$

$$+ \frac{2\lambda^2 \Delta T}{R_e \Delta R^2} [2W(R^+) - W(T^-)]$$

$$+ \frac{2\Delta T}{R_e \Delta Z^2} [W(Z^+) + W(Z^-) - W(T^-)]$$

$$+ W(T^-) \} / \left\{ 1 + \frac{2\lambda^2 \Delta T}{R_e \Delta R^2} + \frac{2\Delta T}{R_e \Delta Z^2} \right\} \quad (16)$$

$$D(T^+) = - \frac{2\lambda \Delta T}{\Delta R} U(R^+)$$

$$- \frac{\Delta T}{\Delta Z} [W(Z^+) - W(Z^-)] + D(T^-). \quad (17)$$

**At the liquid-air interface, ( $R = 1$ ),**

$$U = 0 \quad (18)$$

$$V(T^+) = \left\{ - \frac{\Delta T}{\Delta Z} W [V(Z^+) - V(Z^-)] \right.$$

$$+ \frac{\lambda^2 \Delta T}{R_e \Delta R^2} [2V(R^-) - 4(R^-) + V(T^-)]$$

$$+ \frac{2\Delta T}{R_e \Delta Z^2} [V(Z^+) + V(Z^-) - V(T^-)]$$

$$+ V(T^-) \} / \left\{ 1 - \frac{\lambda^2 \Delta T}{R_e \Delta R^2} + \frac{2\Delta T}{R_e \Delta Z^2} \right\} \quad (19)$$

$$\begin{aligned}
W(T^+) = & \left\{ -\frac{\Delta T}{\Delta Z} W [W(Z^+) + W(Z^-)] \right. \\
& - \frac{\Delta T}{\delta \Delta Z} [D(Z^+) - D(Z^-)] \\
& + \frac{\lambda^2 \Delta T}{R_e \Delta R^2} [2W(R^{--}) - 4W(R^-) + W(T^-)] \\
& + \frac{2 \Delta T}{R_e \Delta Z^2} [W(Z^+) + W(Z^-) - W(T^-)] \\
& \left. + W(T^-) \right\} / \left\{ 1 - \frac{\lambda^2 \Delta T}{R_e \Delta R^2} + \frac{2 \Delta T}{R_e \Delta Z^2} \right\} \quad (20)
\end{aligned}$$

$$\begin{aligned}
D(T^+) = & \frac{2 \lambda \Delta T}{\Delta R} U(R^-) \\
& - \frac{\Delta T}{\Delta Z} [W(Z^+) - W(Z^-)] + D(T^-). \quad (21)
\end{aligned}$$

Along the rotating disk, ( $Z = 0$ ),

$$U = 0 \quad (22)$$

$$V = R \quad (23)$$

$$W = 0 \quad (24)$$

$$D(T^+) = \left[ -2 \frac{\Delta T}{\Delta Z} [W(Z^+) - W(Z^-)] + D(T^-) \right] \frac{T \Delta S}{\Delta Z \Delta R} \quad (25)$$

Along the stationary disk ( $Z = 1$ ),

$$U = 0 \quad (26)$$

$$V = 0 \quad (27)$$

$$((T^-) W + (A) W) \frac{T \Delta S}{\Delta Z \Delta R} + W = 0 \quad (28)$$

$$D(T^+) = -2 \frac{\Delta T}{\Delta Z} [W(Z) - W(Z^-)] + D(T^-) \quad (29)$$

The above equations (to obtain steady state solutions) were programmed for a digital computer. Such solutions are considered to have been achieved when  $D(T^+)$  and  $D(T^-)$  are approximately equal.

A copy of the computer program, coded in Fortran IV, is contained in Appendix A.

$$(45) \quad ((T^-) \alpha + [(-S) W - (A) W]) \frac{T \Delta S}{\Delta Z} = (T^+) \alpha$$

$\{0 = S\}$  xelb gmitator edl grolA

$$(55) \quad 0 = U$$

$$(65) \quad A = V$$

$$(75) \quad 0 = W$$

## КОМПУТЕРНАЯ СИСТЕМА ДЛЯ ИМУНИТИ

### IV. STABILITY

Чтобы сохранить числовые вычисления стабильными, необходимо, чтобы

если движение подчинено закону сохранения массы, то  
если движение подчинено закону сохранения импульса, то  
если движение подчинено закону сохранения энергии, то  
если движение подчинено закону сохранения момента импульса, то

If the flow under consideration is to remain incompressible  
and therefore stable, Chorin asserts that  $\delta$  must be chosen so that

$$\delta^{\frac{1}{2}} R_e \frac{\text{Max}}{R, Z} (U^2 + V^2 + W^2)^{\frac{1}{2}} < 1.$$

This is equivalent to keeping the artificial Mach Number less than  
единицу.

To insure that motion can be adequately described in the con-  
fines of a given grid scheme  $\Delta T$  must be chosen so that

$$\Delta T \leq .437 \text{ Min } (\Delta R \text{ or } \Delta Z) \delta^{\frac{1}{2}}.$$

Numerical results show that the above conditions are not sufficient  
for stability in some cases and too restrictive in others.

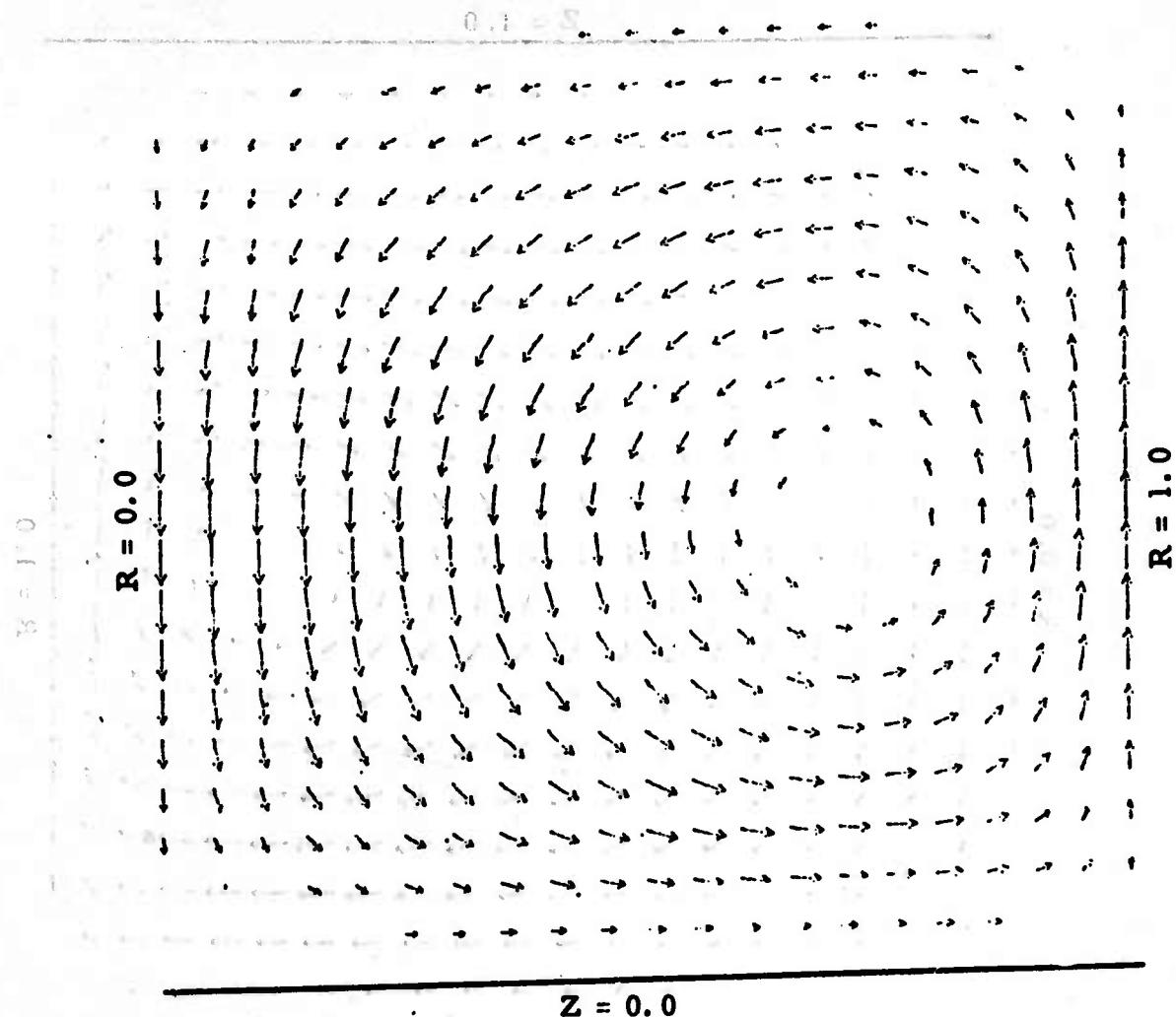
## V. NUMERICAL RESULTS AND DISCUSSION

The secondary flows found in the R-Z plane are shown for  $\lambda = 1.0, .50, .20$  and  $.10$  in Figures 3 through 6. ( $\lambda R_e = 1.0$  in each case.) Computer program outputs for velocities and pressures corresponding to these cases are given in Appendix B.

Once an adequate  $\delta$  and  $\Delta T$  are chosen, convergence is achieved in 2000 to 4000 iterations. This requires 20 to 40 minutes of computer time. The following table contains  $\delta$  and  $\Delta T$  values for which divergence occurs:

$\lambda$	$R_e$	Trial Values		Necessary Conditions	
		$\delta$	$\Delta T$	$\delta$	$\Delta T$
.75	1.0	.04	.001	1.0	.022
.75	1.0	.09	.001	1.0	.022
.75	1.0	.16	.001	1.0	.022
1.0	1.0	.04	.0005	1.0	.022

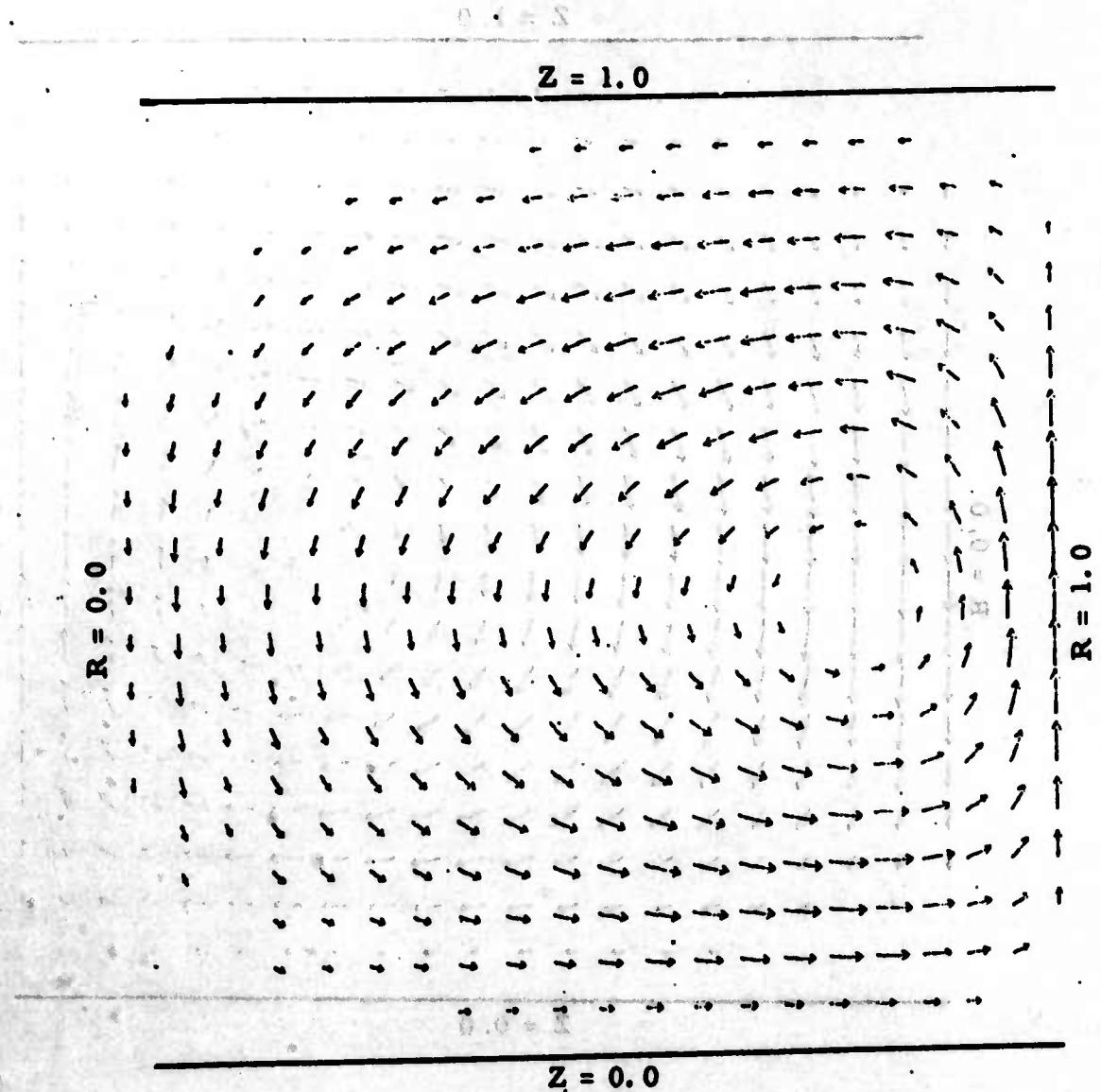
$Z = 1.0$



**Figure 3. Secondary Velocity Field**

$(\lambda = 1.0, R_e = 1.0)$

Scale: .25" = .00458

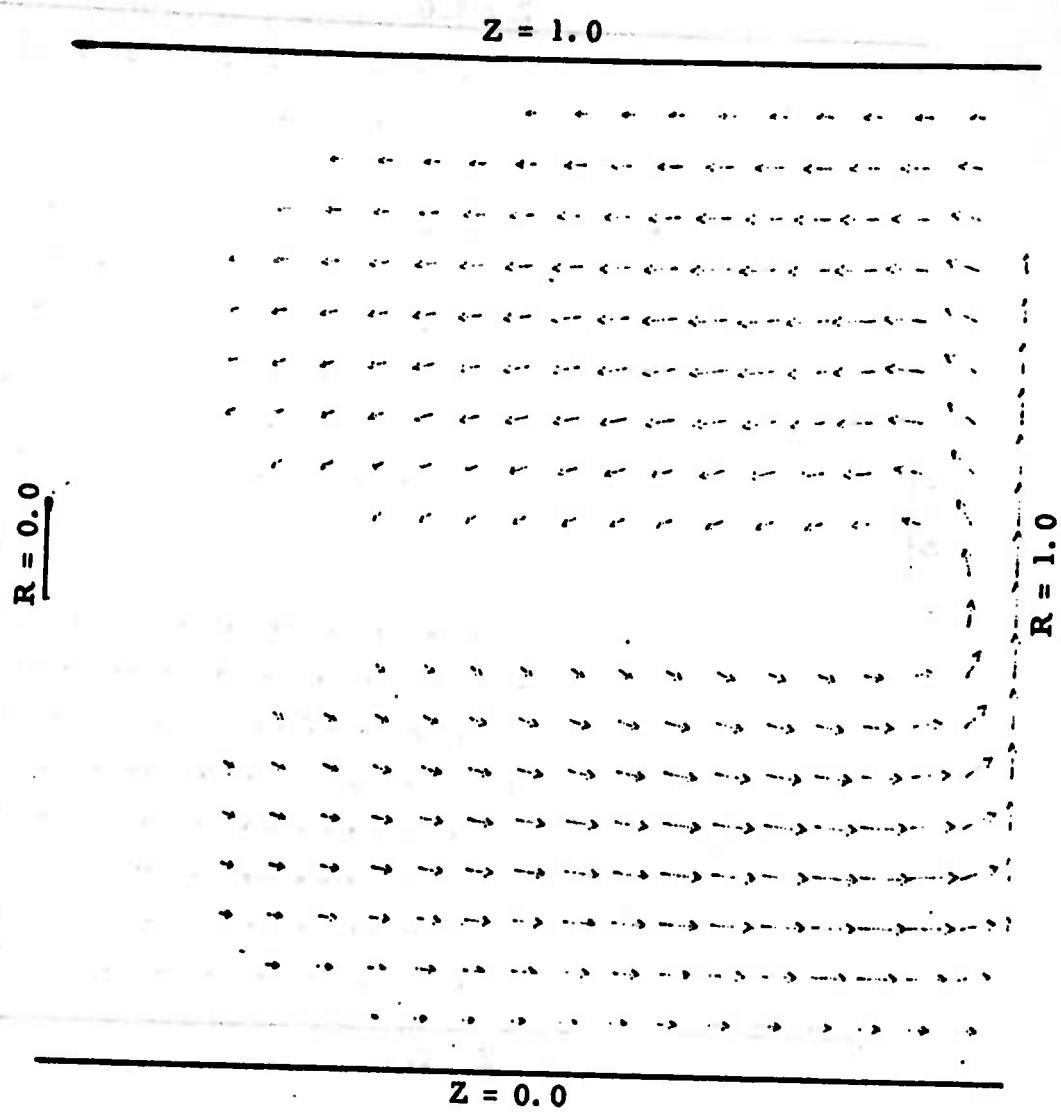


Secondary Velocity Field Plot

**Figure 4.0 Secondary Velocity Field**

$(\lambda = .5, R_e = 2.0)$

Scale:  $.25'' = .00636$



**Figure 5. Secondary Velocity Field**

$(\lambda = .2, R_e = 5.0)$

Scale:  $.25'' = .00677$

Z = 1.0

R = 0.0

R = 1.0

Z = 0.0

**Figure 6. Secondary Velocity Field**  
~~Blunt nosed V-shaped wedge~~ ~~symmetry~~  
 $(\lambda = .1, R_e = 10.0)$   
 $(0 \leq \theta \leq 180^\circ)$   
Scale: .25" = .00740

Listed below are  $\delta$  and  $\Delta T$  values for which there are convergent solutions:

$\delta$	$R_e$	Trial Values		Chorin's Necessary Conditions	
		$\delta$	$\Delta T$	$\delta$	$\Delta T$
1.0	1.0	.04	.00025	1.0	.022
.75	1.0	.04	.00075	1.0	.022
.75	1.0	.04	.00075	1.0	.022
.75	1.0	.09	.00075	1.0	.022
.75	1.0	.16	.0005	1.0	.022
.75	1.0	.16	.00075	1.0	.022
.75	10.0	.04	.0005	.01	.002 *
.50	1.0	.09	.001	1.0	.022
.50	2.0	.04	.001	.25	.011
.20	1.0	.09	.001	1.0	.022
.20	5.0	.04	.0005	.04	.004
.20	5.0	.04	.001	.04	.004
.10	1.0	.04	.001	1.0	.022
.10	10.0	.04	.001	.01	.002 *
.10	5.0	.04	.001	.04	.004

\* The necessary conditions are violated, yet a convergent solution is obtained.

At least 20 grid spaces are necessary in R and Z for reasonable results. Numerical oscillations are produced in the Z direction when only ten grid spaces are used.

For the small secondary flows, true convergence is very difficult to discern with this numerical technique. As an example, for  $\lambda = .1$  and  $R_e = 5.0$  convergence seems to have been achieved in 2000 iterations. But when the results are plotted, numerical oscillations in U are evident. However, after 4000 iterations these oscillations have vanished and the results appear to be accurate when compared with the infinite disk solution.

Rate of convergence is independent of starting values unless accurate values at  $R = 1.0$  for W are introduced. In proof of this, a case was run which took as an initial state the infinite disk solution. Convergence still required 2000 iterations.

In order to test the stability of the numerical solution, two special computer runs were made. In the first, a convergent solution was perturbed in W. This perturbation was of the order  $\text{Max}_{R, Z} |W|$  and was introduced between  $R = 0.5$  and 0.6. The solution again converged, suggesting stability for finite perturbations. For the second run, initial values were assumed from the infinite disk solution and pressure was increased by an order of magnitude. This solution achieved an oscillatory behavior then diverged completely.

## VI. CONCLUSIONS

A large scale parametric examination of  $\delta$ ,  $\Delta T$ ,  $\Delta R$  and  $\Delta Z$  is required to best determine the numerical stability, the rate of convergence, and the accuracy of each problem solved using Chorin's technique. To show that the results obtained herein are indeed reasonable a numerical solution is compared with a series solution for infinite disks. The series solutions are written to second order in  $\lambda R_e$  as follows [2, 3]:

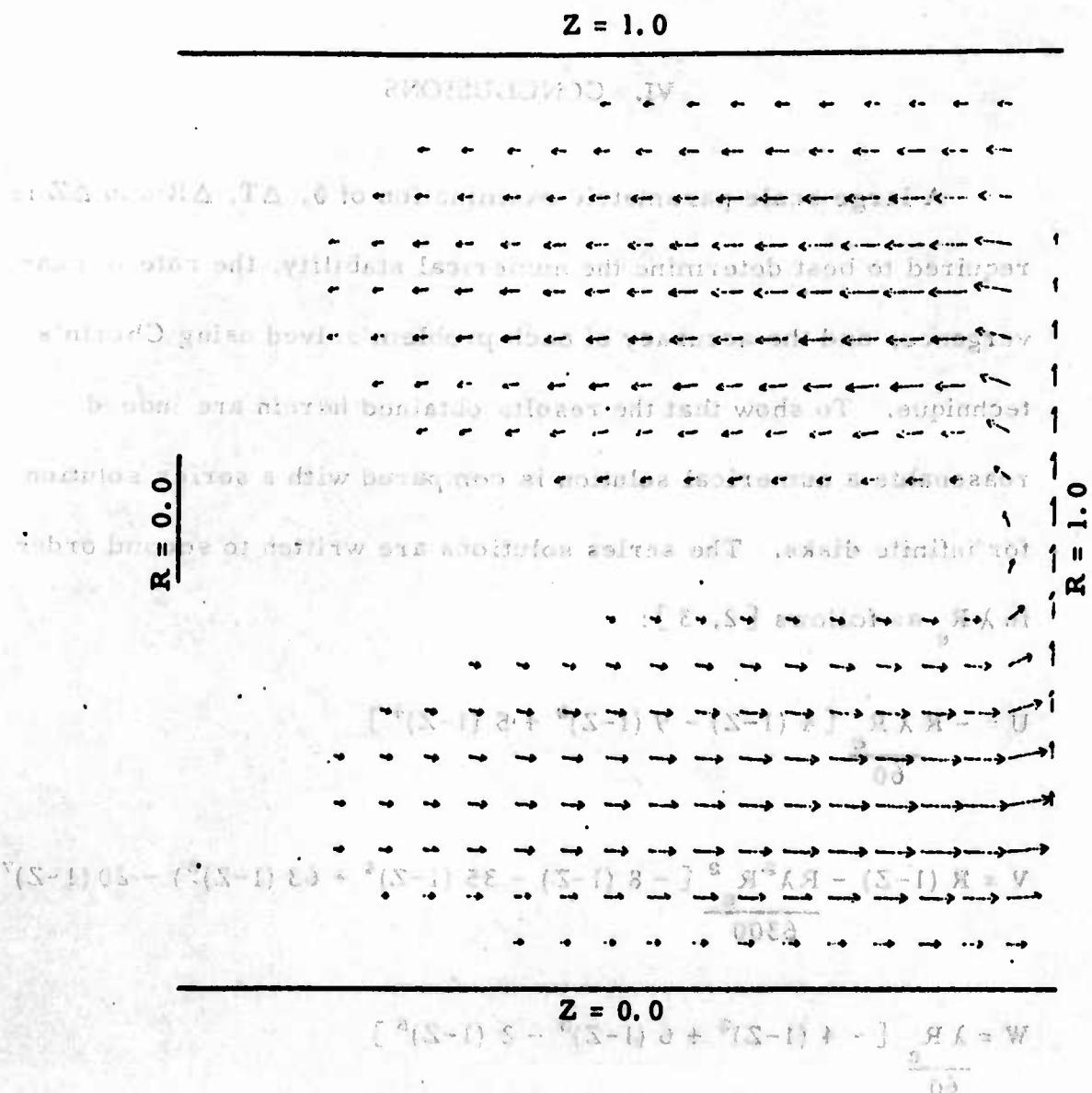
$$U = - \frac{R \lambda R_e}{60} [ 4(1-Z) - 9(1-Z)^2 + 5(1-Z)^4 ]$$

$$V = \frac{R(1-Z) - R\lambda^2 R_e^2}{6300} [ -8(1-Z) - 35(1-Z)^4 + 63(1-Z)^6 - 20(1-Z)^7 ]$$

$$W = \frac{\lambda R_e}{60} [ -4(1-Z)^2 + 6(1-Z)^3 - 2(1-Z)^5 ]$$

$$P = .15 R^3.$$

These comparisons are made for  $\lambda = .1$  and  $R = 5.0$ . Figure 7 shows the secondary velocity field for the numerical solution. (A computer output for this solution is contained in Appendix B.)

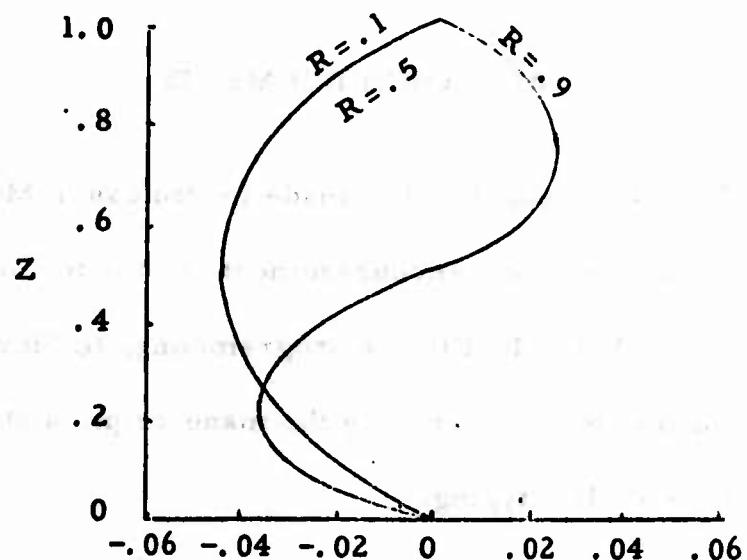


**Figure 7. Secondary Velocity Field**

( $\lambda = .1$ ,  $R_e = 5.$ )

Scale: .25" = .00369

**Figure 8 shows a graphical representation of a comparison between the numerical solution for finite disks and the series solution for infinite disks.**



**Figure 8.**

$$\frac{U - U_\infty}{R \operatorname{Max} \frac{U}{R, Z}}$$

Considering the closeness of the results of the above comparison it can definitely be stated that the velocity and pressure for rotating disk viscometer applications are adequately represented by the series solution of the infinite disk problem.

## ACKNOWLEDGEMENTS

Grateful acknowledgement is made to Professor Morton M. Denn for his assistance and encouragement, to Monte Coleman for assistance with CALCOMP Plotter programming, to Muriel Ewing for helpful suggestions in preparing the manuscript, and to Alcise Beatty for the excellent typing.

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## APPENDIX A

### COMPUTER PROGRAM

#### Coding hints:

1. Factor all constants and remove their computation from the innermost integration loop. This results in a 30% reduction of computer time.

2. Simplify the subscript arithmetic as much as possible.

(See statement number 5.) This results in a 20% reduction of computer time.

DIMENSION U(51,21,3), V(51,21,3), W(51,21,3), O(51,21,3), R(51), Z(21)  
 REAL LAM  
 REAL LAM2  
 READ(5,51) LAM, RE, DEL, DT, DR, DZ, L, M  
 N=1  
 R(1)=0.  
 Z(1)=0.  
 LM1=L-1  
 MM1=M-1  
 DO 2 I=1,LM1-1  
 2 R(I+1)=R(I)+DR  
 DO 20 I=1,MM1  
 20 Z(I+1)=Z(I)+DZ  
 DO 3 I=1,L  
 DO 3 J=1,M  
 DO 3 K=1,3  
 U(I,J,K)=0.0  
 V(I,J,K)=0.0  
 W(I,J,K)=0.0  
 D(I,J,K)=0.0  
 DO 4 I=1,L  
 DO 4 K=1,3  
 4 V(I,1,K)=R(I)  
 WRITE(6,52)  
 LAM2=LAM\*\*2  
 DR2=DR\*\*2  
 CZ2=DZ\*\*2  
 DIV1=1.0+DT\*(-LAM2/DR2+2.0/DZ2)/RE  
 DIV=1.0+2.0\*DT\*(LAM2/DR2+1.0/DZ2)/RE  
 RDIV=1.0/DIV

1

2  
20

3

4

RDIV1=1.0/DIV1

C1=LAH\*DT/DR  
C2=2.0\*LAH\*DT  
C3=DT/DT  
C4=LAH\*DT/(DR\*DEL)  
C5=2.0\*LAH2\*DT/(RE\*DR)  
C6=LAH2\*DT/(RE\*DR)  
C7=2.0\*LAH2\*DT/RE  
C8=2.0\*DT/IRE\*DR2)  
C9=DT/(DEL\*DR)  
C10=LAH2\*DT/(RE\*DR2)  
C11=DT/(DEL\*DR2)  
C12=2.0\*DT/DR  
C13=2.0\*LAH\*DT/DR

5 DO 6 J=2,MM1

NJP=J\*51

NJN=(J-2)\*51

DO 6 I=2,LH1

I=J+NJ+I\*(I+DT)

DJP=NJP+N

IJN=NJN+I\*DT

U(IJ+1,3)=(-U(IJ,1,2)\*(U(IJ+1,1,2)-U(IJ-1,1,2))+C1

+C2\*V(IJ,1,2)\*\*2/R(I)

-W(IJ,1,2)\*(U(IJP,1,2)-U(IJN,1,2))\*C3

-D(IJ+1,1,2)-D(IJ-1,1,2))\*C4

+U(IJ+1,1,2)+U(IJ-1,1,2)-U(IJ,1,1))\*C5

+C6\*(U(IJ+1,1,2)-U(IJ-1,1,2))/R(I)

-C7\*(U(IJ,1,2)/R(I)\*\*2+D<sub>11</sub>\*DT\*DT)

+U(IJP,1,2)+U(IJN,1,2)-U(IJ,1,1))\*C8

50

DEFINITION n(2)\*5T\*3)+A(2)\*5T\*2)+N(2T\*5T\*3)+N(2T\*5T\*5T)+N(2T\*5T\*5T\*5T)

```

S+U(IJ,1,1))*RDIV
V(IJ,1,3)=(-U(IJ,1,2)*V(IJ,1,2)*(V(IJ+1,1,2)-V(IJ-1,1,2))*C1
S-C2*U(IJ,1,2)*V(IJP,1,2)/R(I)
S-N(IJ,1,2)*(V(IJP,1,2)-V(IJN,1,2))*C3
S+(V(IJ+1,1,2)+V(IJ-1,1,2)-V(IJ,1,2))*C5
S+C6*(V(IJ+1,1,2)-V(IJ-1,1,2))/R(I)
S-C7*V(IJ,1,2)/R(I)*#2
S+(V(IJP,1,2)+V(IJN,1,2)-V(IJ,1,2))*C8
S+V(IJ,1,1))*RDIV
W(IJ,1,3)=(-U(IJ,1,2)*(W(IJ+1,1,2)-W(IJ-1,1,2))*C1
S-N(IJ,1,2)*(W(IJP,1,2)-W(IJN,1,2))*C3
S-(D(IJP,1,2)-D(IJN,1,2))*C9
S+(W(IJ+1,1,2)+W(IJ-1,1,2)-W(IJ,1,2))*C5
S+C6*(W(IJ+1,1,2)+W(IJ-1,1,2))/R(I)
S+(W(IJP,1,2)+W(IJN,1,2)-W(IJ,1,2))*C8
S+W(IJ,1,1))*RDIV
D(IJ,1,3)=-C2*U(IJ,1,2)/R(I)
S-(U(IJ+1,1,2)-U(IJ-1,1,2))*C1
S-(W(IJP,1,2)-W(IJN,1,2))*C3+D(IJ,1,1)
CONTINUE
DO 7 J=2,MM1
V(L,J,3)=((2.0*V(L-2,J,2)-4.0*V(L-1,J,2)+V(L,J,1))*C10
S-W(L,J,2)*(V(L,J+1,2)-V(L,J-1,2))*C3
S+(V(L,J+1,2)+V(L,J-1,2)-V(L,J,1))*C8
S+V(L,J,1))*RDIV1
C
W(I,J,3)=(-W(I,J,2)*(W(I,J+1,2)-W(I,J-1,2))*C3
S-(D(I,J+1,2)-D(I,J-1,2))*C11
S+(2.0*W(I,J,2)-W(I,J,1))*C5
S+(W(I,J+1,2)+W(I,J-1,2)-W(I,J,1))*C8

```

```

S+H(L,J,1))*RDIV
H(L,J,3)=(-H(L,J,2)*(H(L,J+1,2)-H(L,J-1,2))*C3
S-(D(L,J+1,2)-D(L,J-1,2))*C11
S+(2.0*M(L-2,J,2)-4.0*M(L-1,J,2)+M(L,J,1))*C10
S+(H(L,J+1,2)+H(L,J-1,2)-H(L,J,1))*C8
S+H(L,J,1))*RDIV1
CONTINUE
DO 8 I=1,L
D(I,1,3)=-(H(I,2,2)-H(I,1,2))*C12+D(I,1,1)
D(I,M,3)=-(H(I,M,2)-H(I,M-1,2))*C12+D(I,M,1)
CONTINUE
DO 9 J=2,MH1
D(1,J,3)=-U(2,J,2)*C13
S-(H(1,J+1,2)-H(1,J-1,2))*C3
S+D(1,J,1)
CONTINUE
D(L,J,3)=-(U(L,J,2)-U(L-1,J,2))*C3
S-(H(L,J+1,2)-H(L,J-1,2))*C13
S+D(L,J,1)
CONTINUE
DO 10 I=1,L
DO 10 J=1,M
U(I,J,2)=U(I,J,3)
U(I,J,1)=U(I,J,2)
V(I,J,2)=V(I,J,3)
V(I,J,1)=V(I,J,2)
W(I,J,2)=W(I,J,3)
W(I,J,1)=W(I,J,2)

```

```

W(I,J,1)=W(I,J,2)
D(I,J,2)=D(I,J,3)
D(I,J,1)=D(I,J,2)
CONTINUE
DMAX=0.0
DO 100 I=1,L
  DO 100 J=1,M
    DMAX=AMAX1(DMAX,ABS(D(I,J,3)))
    IF(DMAX.GT.1.0)GO TO 101
    N=N+1
    IF(MOD(N,100).NE.0)GOTO 5
    WRITE(6,53)N
    WRITE(6,51)LMH,RE,DEL,DT,DR,DZ,L,M
    WRITE(6,54)
    LM1=LM1/10
    JM1=MM1/10
    J=H
    WRITE(6,50)(U(I,J,3),I=1,L,LMT)
    J=J-JMT
    IF(J.GT.0)GOTO 11
    WRITE(6,52)
    WRITE(6,55)
    J=N
    WRITE(6,50)(V(I,J,3),I=1,L,LMT)
    J=J-JMT
    WRITE(6,52)
    IF(J.GT.0)GOTO 12
    WRITE(6,56)
    J=N
    WRITE(6,50)(W(I,J,3),I=1,L,LMT)
  101
  11
  12
  13

```

```

J=J-JMT
13 IF (J.GT.0) GOTO 13
      WRITE(6,52)
      WRITE(6,57)
      J=N
      WRITE(6,50)(0(I,J,3),I=1,L,LMT)
14      J=J-JMT
      IF (J.GT.0) GOTO 14
      IF (N.LT.4000.AND.DMAX.LT.1.0) GOTO 10 5
      GOTO 1
      STOP
      50 FORMAT(1IF7.5)
      51 FORMAT(6F10.6,2I10)
      52 FORMAT(1F10.6,2I10)
      53 FORMAT(3H1N-,15)
      54 FORMAT(2H U)
      55 FORMAT(2H V)
      56 FORMAT(2H W)
      57 FORMAT(2H D)
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## APPENDIX B

### SAMPLE COMPUTER OUTPUTS

#### Guide to the computer output:

1. The first line of print is the number of iterations.
2. The second line of print is  $\lambda$ ,  $R_e$ ,  $\delta$ ,  $\Delta T$ ,  $\Delta R$ ,  $\Delta Z$  and a pair of indices.
3. The velocity fields (U, V, W) and the density ( $D = \delta P$ ) are printed on the following lines. The numbers are oriented so as to correspond to the graphs previously shown.

$$N=4000 \quad 1.000000 \quad 1.000000 \quad 0.040000 \quad 0.000250 \quad 0.050000 \quad 0.050000$$

21

42

W	• 000000 • 000000 • 000000 • 000000 • 000000 • 000000 • 000000 • 000000 • 000000 • 000000 • 000000 • 000000 -• 00062-• 00054-• 00050-• 00045-• 00039-• 00030-• 00018-• 00003 • 00015 • 00036 • 00056 -• 00170-• 00165-• 00158-• 00145-• 00125-• 00096-• 00057-• 00007 • 00052 • 00116 • 00173 -• 00287-• 00281-• 00287-• 00278-• 00256-• 00220-• 00168-• 00097-• 00009 • 00095 • 00203 • 00296 -• 00381-• 00386-• 00374-• 00346-• 00297-• 00226-• 00131-• 00011 • 00129 • 00275 • 00397 -• 00428-• 00435-• 00424-• 00392-• 00338-• 00259-• 00151-• 00014 • 00146 • 00314 • 00456 -• 00413-• 00421-• 00411-• 00382-• 00332-• 00256-• 00153-• 00020 • 00140 • 00311 • 00458 -• 00337-• 00342-• 00335-• 00312-• 00273-• 00215-• 00133-• 00024 • 00110 • 00261 • 00395 -• 00215-• 00214-• 00208-• 00195-• 00173-• 00138-• 00090-• 00023 • 00064 • 00168 • 00268 -• 00082-• 00076-• 00073-• 00068-• 00060-• 00049-• 00034-• 00011 • 00019 • 00059 • 00104 • 00000 • 00000 • 00000 • 00000 • 00000 • 00000 • 00000 • 00000 • 00000 • 00000 • 00000 • 00000
D	-• 00623-• 00496-• 00393-• 00312-• 00237-• 00157-• 00065 • 00038 • 00148 • 00253 • 00338 -• 00599-• 00470-• 00353-• 00261-• 00185-• 00113-• 00037 • 00043 • 00125 • 00198 • 00248 -• 00598-• 00453-• 00328-• 00234-• 00161-• 00096-• 00030 • 00039 • 00108 • 00171 • 00218 -• 00550-• 00417-• 00305-• 00222-• 00157-• 00098-• 00037 • 00029 • 00097 • 00163 • 00222 -• 00439-• 00351-• 00276-• 00218-• 00167-• 00114-• 00053 • 00015 • 00090 • 00169 • 00247 -• 00281-• 00260-• 00239-• 00216-• 00183-• 00137-• 00076-• 00001 • 00085 • 00182 • 00286 -• 00106-• 00162-• 00201-• 00216-• 00202-• 00163-• 00101-• 00021 • 00078 • 00195 • 00331 -• 00045-• 00077-• 00167-• 00214-• 00217-• 00185-• 00125-• 00041 • 00067 • 00202 • 00371 -• 00140-• 00019-• 00139-• 00204-• 00218-• 00193-• 00139-• 00060 • 00047 • 00192 • 00391 -• 00173 • 00016-• 00105-• 00172-• 00190-• 00173-• 00131-• 00069 • 00019 • 00148 • 00359 • 00221 • 00064-• 00045-• 00099-• 00113-• 00103-• 00081-• 00050-• 00009 • 00057 • 00194

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	00078-	00082-	00087-	00091-	00093-	00090-	00090-	00079-	00050	00012	00115	00239		
	00135-	00149-	00159-	00165-	00167-	00162-	00162-	00141-	00087	00024	00206	00415		
	00181-	00204-	00218-	00226-	00228-	00220-	00220-	00191-	00117	00033	00280	00558		
	000203-	00232-	00247-	00256-	00258-	00249-	00249-	00216-	00133	00036	00317	00636		
	00194-	00222-	00237-	00245-	00248-	00240-	00240-	00209-	00132	00028	00304	00629		
	00156-	00177-	00188-	00195-	00198-	00192-	00192-	00169-	00111	00015	00242	00527		
	00096-	00106-	00113-	00118-	00120-	00117-	00117-	00104-	00071	00003	00145	00344		
	00034-	00034-	00037-	00039-	00040-	00039-	00039-	00035-	00025-	00002	00047	00125		
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$$N = 4000$$



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